## MINIMAX RATES OF CLUSTERING MIXTURE MODELS AND STOCHASTIC BLOCK MODELS

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Clustering and community detection: tasks of grouping objects together.

- **Clustering**: objects are *n* points  $X_1, \dots, X_n$  in  $\mathbb{R}^d$ .
- **Community detection**: objects are the *n* vertices of a graph with adjacency matrix  $A \in \{0, 1\}^{n \times n}$ .

**Toy-models** :  $z \in [k]^n$  cluster labeling vector.

- (isotropic) Gaussian mixture model (GMM):  $X_i | z_i \sim Nor(\mu_{z_i}, \sigma^2 I_d)$ ;
- ► (homogeneous) stochastic block model (SBM):  $A_{ij} | z_i, z_j \sim \begin{cases} Ber(p) & \text{if } z_i = z_j, \\ Ber(q) & \text{otherwise.} \end{cases}$  for i < j and  $A_{ji} = A_{ji}$ .

**Statistical problem** : recover z (up to a permutation) based on the observation of X or A only (we also assume k is known).

### INTRODUCTION MINIMAX RATES IN THESE TWO PROBLEMS (1)

For any  $z \in [k]^n$ , denote  $n_a(z) = \sum_{u \in [n]} \mathbb{1}\{z_u = a\}$  the size of cluster  $a \in [k]$ . Let  $\beta > 1$  and define

$$\mathcal{Z}_{n,k,\beta} = \left\{ z \in [k]^n \colon n_a(z) \in \left[\frac{n}{\beta k}, \beta \frac{n}{k}\right] \forall a \in [k] \right\}.$$

Let  $\hat{z}$  be an estimator of z. We define the *loss* of  $\hat{z}$  as

$$\operatorname{loss}(z,\hat{z}) = \min_{\tau \in \operatorname{Sym}(k)} \frac{1}{n} \sum_{u=1}^{n} \mathbb{1}\{z_u \neq \tau(\hat{z}_u)\},$$

where Sym(k) is the group of permutations of [k] (we can only recover the *partition*, not the *labels*).

**Aim**: study the *expected loss*  $\mathbb{E}[loss(\hat{z}, z)]$  of an estimator  $\hat{z}$  (where expectation is taken with respect to *X* or *A* being generated from GMM or SBM.

**Intuitive**: difficulty of estimating *z* is governed by :

- for GMM: separation between the centers  $\mu_1, \dots, \mu_k$  (assuming  $\sigma$  fixed);
- ▶ for SBM: difference between Ber(*p*) and Ber(*q*).

INTRODUCTION MINIMAX RATES IN THESE TWO PROBLEMS (2)

### Theorem 1 (Lu and Zhou, 2016: minimax rate in isotropic GMM)

Let  $\Delta = \min_{a \neq b} \|\mu_a - \mu_b\|_2$ . Suppose  $\frac{\Delta}{\sigma \log(k)} \gg 1$ . Then,

$$\inf_{\hat{z}} \sup_{z \in \mathcal{Z}_{n,k,\beta}} \mathbb{E}_{X \sim \mathsf{GMM}(z,\mu_1,\cdots,\mu_k)} \left[ \operatorname{loss}(\hat{z},z) \right] \ \asymp \ \exp\left(-(1+o(1))\frac{\Delta^2}{8\sigma^2}\right).$$

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#### Theorem 2 (Zhang and Zhou, 2016: minimax rate in homogeneous SBM)

Let  $I = \text{Ren}_{1/2}(\text{Ber}(p), \text{Ber}(q)) = -2 \log \left(\sqrt{pq} + \sqrt{(1-p)(1-q)}\right)$  the Rényi divergence of order 1/2 between two Bernoulli distributions. Suppose  $\beta \in (1, \sqrt{2})$ , and let q < p. If  $\frac{nl}{k \log k} \gg 1$  we have

$$\inf_{\hat{z}} \sup_{z \in \mathcal{Z}_{n,k,\beta}} \mathbb{E}_{G \sim \text{SBM}(z,p,q)} \left[ \text{loss}(\hat{z},z) \right] \asymp \begin{cases} \exp\left(-(1+o(1))\frac{nl}{2}\right) & \text{if } k = 2, \\ \exp\left(-(1+o(1))\frac{nl}{\beta k}\right) & \text{if } k \geq 3. \end{cases}$$

Rate optimal algorithms:

- GMM: Lloyd's algorithm (Lu & Zhou, 2016); spectral clustering (Löffler et al., 2021);
- SBM: MLE (Zhang & Zhou, 2016); two-stage algorithms (Gao et al., 2017); semidefinite programs (Fei & Chen, 2018); VEM (Zhang & Zhou, 2020); spectral clustering (Zhang, 2023).

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### FROM ISOTROPIC TO ANISOTROPIC GMM MINIMAX RATES: NEW SNRS

Recall in isotropic GMM:  $\inf_{\hat{z}} \sup_{z \in \mathbb{Z}_{n,k,\beta}} \mathbb{E}_{X \sim \text{GMM}(z,\mu_1,\cdots,\mu_k)} [\operatorname{loss}(\hat{z},z)] \asymp \exp\left(-(1+o(1))\frac{\text{SNR}^2}{8}\right)$  where  $\text{SNR} = \frac{\min_{a \neq b} \|\mu_a - \mu_b\|}{\sigma}$ .

MINIMAX RATES: NEW SNRs

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$$\min_{a\neq b} \|\Sigma^{-1/2}(\mu_a - \mu_b)\|_2 = \min_{a\neq b} \|\mu_a - \mu_b\|_{\Sigma} \quad \text{(Mahalanobis distance)}.$$

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**GMM with inhomogeneous Covariance Matrices**:  $X_i | z_i \sim \text{Nor}(\mu_{z_i}, \sum_{z_i})$ Chen and Zhang, 2021 show that the SNR should be replaced by  $\min_{a \neq b} \text{SNR}'_{a,b}$ 

MINIMAX RATES: NEW SNRs

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$$SNR'_{a\neq b} = 2\min_{x\in\mathcal{B}_{ab}} \|x\|$$

$$\begin{split} \mathcal{B}_{a,b} &= \left\{ x \in \mathbb{R}^{d} \colon x^{T} \Sigma_{a}^{1/2} \Sigma_{b}^{-1} (\mu_{a} - \mu_{b}) + \frac{1}{2} x^{T} \left( \Sigma_{a}^{1/2} \Sigma_{b}^{-1} \Sigma_{a}^{1/2} - I_{d} \right) x \\ &\leq -\frac{1}{2} (\mu_{a} - \mu_{b})^{T} \Sigma_{b}^{-1} (\mu_{a} - \mu_{b}) + \frac{1}{2} \log |\Sigma_{a}| - \frac{1}{2} \log |\Sigma_{b}| \right\}. \end{split}$$





**(b)** After transformation  $Y = \Sigma_1^{-1/2} (Y - \theta_1)$ .

**Figure.** A geometric interpretation of SNR'<sub>12</sub> (taken from Chen and Zhang, 2021).

WHERE DOES THIS COME FROM?

#### Lemma 1 (Testing Error for Quadratic Discriminant Analysis (Chen & Zhang, 2021))

Consider two hypotheses  $H_0$ :  $Y \sim Nor(\mu_1, \Sigma_1)$  and  $H_1$ :  $Y \sim Nor(\mu_2, \Sigma_2)$ . Define a testing procedure

 $\phi(x) = \mathbb{1}\{\log f_1(x) < \log f_2(x)\} = \mathbb{1}\left\{\log |\Sigma_1| + (x - \mu_1)^T \Sigma_1^{-1} (x - \mu_1) \ge \log |\Sigma_2| + (x - \mu_2)^T \Sigma_2^{-1} (x - \mu_2)\right\}.$ 

Then  $\inf_{\hat{\phi}}(\mathbb{P}_{H_0}(\hat{\phi}=1) + \mathbb{P}_{H_1}(\hat{\phi}=0)) = \mathbb{P}_{H_0}(\phi=1) + \mathbb{P}_{H_1}(\phi=0)$  (Neyman-Pearson). If  $\min\{\mathrm{SNR}'_{1,2}, \mathrm{SNR}'_{2,1}\} \to \infty$ , we have

$$\mathbb{P}_{H_0}(\phi = 1) + \mathbb{P}_{H_1}(\phi = 0) \asymp e^{-(1+o(1))\frac{\left(\min\{SNR'_{1,2}, SNR'_{2,1}\}\right)^2}{8}}$$

 $\textit{Otherwise, } \inf_{\hat{\phi}}(\mathbb{P}_{H_0}(\hat{\phi}=1)+\mathbb{P}_{H_1}(\hat{\phi}=0)) \geq \textit{c for some constant } c>0.$ 

Proof: complicated. Geometric interpretation:  $\approx$  okay

ANOTHER INTERPRETATION

Let  $\mathcal{Y} = (Y_1, \cdots, Y_n)$  and test  $H_0: \mathcal{Y} \sim f^{\otimes n}$  versus  $H_1: \mathcal{Y} \sim g^{\otimes n}$ . If  $f \neq g$  are *independent* of *n*, we have

$$\inf_{\hat{\phi}} (\mathbb{P}_{H_0}(\hat{\phi} = 1) + \mathbb{P}_{H_1}(\hat{\phi} = 0)) \ \asymp \ e^{-(1+o(1)) n \operatorname{Chernoff}(f,g)}$$

where we define the Chernoff information as

Chernoff
$$(f,g) = -\log \inf_{t \in (0,1)} \int f^t(x) g^{1-t}(x) dx.$$

(Note: Chernoff $(f^{\otimes n}, g^{\otimes n}) = n$  Chernoff(f, g). Key observation:  $\mathbb{P}_{H_1}\left(\log \frac{f}{g}(x) > 0\right) = \mathbb{P}\left(e^{t\log \frac{f}{g}(x)} > 1\right) \leq \mathbb{E}_g\left[e^{t\log \frac{f}{g}}\right] = \int f^t g^{1-t} \leq e^{-\text{Chernoff}(f,g)}.$ 

### Remark

- Chernoff  $\left(\operatorname{Nor}(\mu_1, \sigma^2 I_d), \operatorname{Nor}(\mu_2, \sigma^2 I_d)\right) = \frac{\|\mu_1 \mu_2\|_2^2}{8\sigma^2};$
- Chernoff  $(Nor(\mu_1, \Sigma), Nor(\mu_2, \Sigma)) = \frac{1}{8} \|\Sigma^{-1/2}(\mu_1 \mu_2)\|_2^2;$
- Chernoff (Nor(μ<sub>1</sub>, Σ<sub>1</sub>), Nor(μ<sub>2</sub>, Σ<sub>2</sub>)) still complicated
- Provide another interpretation of SNRs.

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### MINIMAX RATES IN MIXTURE MODELS

(NON-GAUSSIAN) MIXTURE MODELS

Mixture model (MM):  $X_i | z_i \sim f_{z_i}$  where  $\mathcal{F} = \{f_1, \dots, f_k\}$  is a family of pdf. Define

$$\operatorname{Chernoff}(\mathcal{F}) = \min_{1 \le a \ne b \le k} \operatorname{Chernoff}(f_a, f_b).$$

### Theorem 3 (Dreveton, Gözeten, Grossglauser, Thiran, 2024)

Suppose Chernoff( $\mathcal{F}$ )  $\gg \log k$ . Then,

$$\min_{\hat{z}} \max_{z \in \mathcal{Z}_{n,\beta}} \mathbb{E}_{X \sim \mathsf{MM}(f_1, \cdots, f_k)} \left[ \operatorname{loss}(z, \hat{z}) \right] = e^{-(1+o(1))\operatorname{Chernoff}(\mathcal{F})}$$

Algorithm 1: Clustering mixture models (known pdf). Input: Set of *n* data points  $(X_1, \dots, X_n) \in \mathcal{X}^n$ , family  $\mathcal{F} = \{f_1, \dots, f_k\}$  of pdfs, number of clusters *k*. Output: Predicted clusters  $\hat{z} \in [k]^n$ . 1 For  $i = 1, \dots, n$  let  $\hat{z}_i^{(t)} = \arg \max_{a \in [k]} \log f(X_i)$ . Return:  $\hat{z} = \hat{z}^{(t_{\max})}$ .

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### LAPLACE MIXTURE MODEL

Algorithm 2: Clustering parametric mixture models.

- **Input:** Set of *n* data points  $(X_1, \dots, X_n) \in \mathcal{X}^n$ , parametric family  $\mathcal{P}_{\Theta} = \{f_{\theta}, \theta \in \Theta\}$  of pdfs, number of clusters *k*, number of iteration  $t_{\max}$ , initial clustering  $\hat{z}^{(0)} \in [k]^n$ .
- 1 For  $t = 1 \cdots t_{max}$  do

1. For 
$$a = 1, \dots, k$$
, let  $\hat{\theta}_a^{(t)} = \hat{\theta}\left(\{X_i : \hat{z}_i^{(t-1)} = a\}\right)$  be an estimate of  $\theta_a$ ;

2. For 
$$i = 1, \dots, n$$
 let  $\hat{z}_i^{(t)} = \arg \max_{a \in [k]} \log f_{\hat{\theta}_a^{(t)}}(X_i)$ .

**Return:**  $\hat{z} = \hat{z}^{(t_{\max})}$ .

Laplace mixture model :  $X_{i\ell} = \mu_{z_i\ell} + \sigma_{z_i\ell}\epsilon_{i\ell}$  where  $\epsilon_{i\ell} \sim \text{Lap}(0, 1)$ .

Novelty : (sub-)exponential tails instead of sub-gaussian.

Estimate mean and variance as:

$$\hat{\mu}(Y_1, \dots, Y_m) = \frac{1}{m} \sum_{i=1}^m Y_i$$
 and  $\hat{\sigma}(Y_1, \dots, Y_m) = \frac{1}{m} \sum_{i=1}^m |Y_i - \hat{\mu}(Y_1, \dots, Y_m)|$ 

### Theorem 4 (Dreveton, Gözeten, Grossglauser, Thiran, 2024)

Suppose  $d = \Theta(1)$ ,  $\sigma_{a\ell} = \Theta(1)$  and  $\|\mu_a - \mu_b\|_1 = \Theta(\rho_n)$  with  $\rho_n \gg \sqrt{k}$  and  $\log(z, \hat{z}^{(0)}) \ll 1/(k\rho_n)$ . Then, the output  $\hat{z}$  of Algorithm 2 after  $\Omega(\log n)$  iterations verifies

 $loss(z, \hat{z}) \leq e^{-(1+o(1))Chernoff(\mathcal{F})}.$ 

#### **Remarks**:

- ▶  $loss(z, \hat{z}^{(0)}) \ll 1/(k\rho_n)$  can be attained by spectral clustering.
- If  $\sigma_{a\ell} = \sigma_{b\ell}$ , then  $\operatorname{Chernoff}(\mathcal{F}) = \min_{1 \le a \ne b \le k} \|\Sigma^{-1}(\mu_a \mu_b)\|_1$ .
- Similar results for other mixture models (such as exponential family mixtures) under sub-exponential assumptions.

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## STOCHASTIC BLOCK MODEL (SBM)

ORIGINAL DEFINITION VS MODERN DEFINITION

Definition 3. Let p(x) be the probability function for a stochastic multigraph, and let  $\{B_1, \ldots, B_t\}$  be a partition of the nodes into mutually exclusive and exhaustive subsets called node-blocks. We say that p(x) is a stochastic blockmodel with respect to the partition  $\{B_1, \ldots, B_t\}$  if and only if

(1) the random vectors  $X_{ii}$  are statistically independent; and

(2) for any nodes  $i \neq j$  and  $i' \neq j'$ , if *i* and *i'* are in the same node-block and *j* and *j'* are in the same node-block, then the random vectors  $X_{ij}$  and  $X_{i'j'}$  are identically distributed.

Figure. Original definition of a SBM by (Holland et al., 1983).

## STOCHASTIC BLOCK MODEL

NEW DEFINITION

- Modern' definition of SBM restricts interactions (edges) to belong to {0, 1};
- Here: generalisation of the 'old' definition. Interactions take value in a space S.
  - Examples: multiplex networks (\$\mathcal{S} = {0, 1}<sup>M</sup>\$), weighted networks (\$\mathcal{S} = \mathbb{R}\_+\$), signed networks (\$\mathcal{S} = {unobserved, observed&present, observed&absent}\$).

**SBM with edge covariates** : Let *f* and *g* be two pdf on *S*. Conditionally on *z*, we observe  $A \in S^{n \times n}$  such that  $A_{ij} = A_{ji}$  is sampled from *f* if  $z_i = z_j$ , and from *g* otherwise. We note  $A \sim \text{SBM}(z, f, g)$ .

Example: 'modern' SBM has  $S = \{0, 1\}$ , f = Ber(p) and g = Ber(q).

Define the *Rényi divergence* of order 1/2 between *f* and *g* as

$$\operatorname{Ren}_{1/2}(f,g) = -2 \log \int \sqrt{\frac{df}{d\mu}} \sqrt{\frac{dg}{d\mu}} d\mu,$$

where  $\mu$  is an arbitrary measure which dominates *f* and *g*.

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### Theorem 5 (Avrachenkov et al., 2020)

Suppose  $\beta \in (1, \sqrt{2})$ , and let  $I = \operatorname{Ren}_{1/2}(f, g)$ . If  $\frac{nl}{k \log k} \gg 1$ , we have

$$\inf_{\hat{z}} \sup_{z \in \mathcal{Z}_{\beta}} \mathbb{E}_{X \sim \text{SBM}(z, f, g)} \left[ \text{loss}(\hat{z}, z) \right] \asymp \begin{cases} \exp\left(-(1 + o(1))\frac{nl}{2}\right) & \text{if } k = 2, \\ \exp\left(-(1 + o(1))\frac{nl}{\beta k}\right) & \text{if } k \geq 3. \end{cases}$$

Furthermore, if  $\frac{n!}{k} = O(1)$  then  $\inf_{\hat{z}} \sup_{z \in Z_{\beta}} \mathbb{E}[loss(\hat{z}, z)] \ge c$  for some constant c > 0.

#### Remarks

- Assumes f and g are known by the algorithm
- ▶ If f and g are unknown: results in (Xu et al., 2020) but with many additional technical conditions

### Questions

- Here the Rényi-divergence is the key quantity. Why?
- Difference between 2 and more than 2 clusters

Two versus more than two communities

### **Two communities**

- ▶ If the two communities are of different sizes (for example  $n_1 > n_2$ ), then nodes in the community 1 have a higher expected degree than nodes in the community 2
- Hence the worst setting is when the two communities are of the same size
- The n/2 in the exponential error rate  $e^{-(1+o(1))\frac{n}{2}I}$  represent the community sizes

### Three (or more) communities

- One could think that having k = 3 communities of size n/k would be the worse, leading to an error rate of  $e^{-(1+o(1))\frac{n}{k}I}$
- ▶ But, the worst case is two small communities of size  $\frac{n}{\beta k}$  and one big of size  $n 2\frac{n}{\beta k}$ . This leads to the minimax rate of  $e^{-(1+o(1))\frac{n}{\beta k}I}$

WHY RÉNYI DIVERGENCE? (1)

**Setting**: n + 1 nodes, two communities of sizes n/2 and n/2 + 1; *f* and *g* denote the pdf for intra- and inter-cluster interactions.

Nodes 1,  $\cdots$ , n/2 in community 1; nodes n/2 + 1,  $\cdots$ , n in community 2. The last node n + 1 belongs either to community 1 or 2.

**Fundamental Testing Problem**: A genie gives you  $z = (\underbrace{1, \dots, 1}_{n/2}, \underbrace{2, \dots, 2}_{n/2}, ?)$ . You have to find  $z_{n+1}$ .

Denote  $X = (A_{n+1,1}, A_{n+1,2}, \dots, A_{n+1,n}) \in S^n$  ( $X_j$  denotes interaction between nodes n + 1 and j) and the two hypothesis:

$$H_1: z_{n+1} = 1$$
 vs  $H_2: z_{n+1} = 2$ .

Under  $H_1$ :  $X \sim f^{\otimes n/2} \otimes g^{\otimes n/2} =: h_1$ , Under  $H_2$ :  $X \sim g^{\otimes n/2} \otimes f^{\otimes n/2} =: h_2$ . MLE:  $\phi_{\text{MLE}}(X) = \begin{cases} H_1 & \text{if } h_1(X) > h_2(X) \\ H_2 & \text{if } h_1(X) \le h_2(X) . \end{cases}$ 

**Guarantee of MLE?** Classic Chernoff–Stein theory of hypothesis testing applies for *f* and *g* independent of *n* (Cover & Thomas, 1999). But generalisation is possible.

## Homogeneous SBM with edge covariates

WHY RÉNYI DIVERGENCE? (2)

Under 
$$H_1$$
:  $X \sim f^{\otimes n/2} \otimes g^{\otimes n/2} =: h_1$ ,  
Under  $H_2$ :  $X \sim g^{\otimes n/2} \otimes f^{\otimes n/2} =: h_2$ .  
MLE:  $\phi_{\text{MLE}}(X) = \begin{cases} H_1 & \text{if } h_1(X) > h_2(X) \\ H_2 & \text{if } h_1(X) \le h_2(X) \end{cases}$ .

Let  $\operatorname{Ren}_t(f, g) = -(1 - t)^{-1} \log \int f^t(x) g^{1-t}(x) dx$  be the Rényi divergence of order *t* between two pdf *f* and *g*, and define the *Chernoff information* 

Chernoff
$$(h_1, h_2) = \sup_{t \in (0,1)} (1-t) \operatorname{Ren}_t(h_1, h_2).$$

### Lemma 2 (Gao, Ma, Zhang, Zhou, 2018; Dreveton et al., 2024)

The worst-case error of  $\phi$ :  $X \mapsto \phi(X) \in \{H_1, H_2\}$  is  $r(\phi) = \max \{\mathbb{P}_{H_1}(\phi(X) = H_2); \mathbb{P}_{H_2}(\phi(X) = H_1)\}$ . We have  $\inf_{\phi} r(\phi) = r(\phi_{MLE})$ . Moreover, if  $Chernoff(h_1, h_2) \gg 1$  we have

$$r(\phi_{\text{MLE}}) = e^{-(1+o(1)\text{Chernoff}(h_1,h_2))}$$

WHY RÉNYI DIVERGENCE? (3)

Under 
$$H_1$$
:  $X \sim f^{\otimes n/2} \otimes g^{\otimes n/2} =: h_1$ ,  
Under  $H_2$ :  $X \sim g^{\otimes n/2} \otimes f^{\otimes n/2} =: h_2$ .  
MLE:  $\phi_{\text{MLE}}(X) = \begin{cases} H_1 & \text{if } h_1(X) > h_2(X) \\ H_2 & \text{if } h_1(X) \le h_2(X) \end{cases}$ .

### Final ingredient:

$$\begin{aligned} \operatorname{Chernoff}(h_1, h_2) &= \sup_{t \in (0, 1)} (1 - t) \operatorname{Ren}_t(\underbrace{f^{\otimes n/2} \otimes g^{\otimes n/2}}_{h_1}, \underbrace{g^{\otimes n/2} \otimes f^{\otimes n/2}}_{h_2}) \\ &= \sup_{t \in (0, 1)} (1 - t) \left[ \sum_{i=1}^{n/2} \operatorname{Ren}_t(f, g) + \sum_{i=n/2+1}^n \operatorname{Ren}_t(g, f) \right] \quad \text{(linearity of Rényi divergence)} \\ &= \frac{n}{2} \sup_{t \in (0, 1)} \left\{ (1 - t) \operatorname{Ren}_t(f, g) + t \operatorname{Ren}_{1 - t}(f, g) \right\} \quad \text{using } (1 - t) \operatorname{Ren}_t(f, g) = t \operatorname{Ren}_{1 - t}(g, f) \\ &= \frac{n}{2} \operatorname{Ren}_{1/2}(f, g). \end{aligned}$$

EXAMPLE: EXACT RECOVERY IN SPARSE SBM

Zero-inflated distribution : Suppose that the distributions *f* and *g* can be written as follows

$$f(x) = (1 - a\rho_n)\delta_0(x) + a\rho_n \tilde{f}(x) \quad \text{and} \quad g(x) = (1 - b\rho_n)\delta_0(x) + b\rho_n \tilde{g}(x), \quad (3.1)$$

When  $\rho_n \ll 1$ , the Rényi divergence  $I = \text{Ren}_{1/2}(f, g)$  between such zero-inflated distributions equals

$$I = (1 + o(1))\rho_n \left[ \left( \sqrt{a} - \sqrt{b} \right)^2 + 2\sqrt{ab} \operatorname{Hel}^2(\tilde{f}, \tilde{g}) \right], \qquad (3.2)$$

where  ${\rm Hel}^2(\tilde{\textit{f}},\tilde{\textit{g}})\in[0,1]$  is the Hellinger divergence defined by

$$\operatorname{Hel}^{2}(f,g) = \frac{1}{2} \int \left( \sqrt{\frac{df}{d\mu}} - \sqrt{\frac{dg}{d\mu}} \right)^{2} d\mu.$$

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### Corollary [Exact recovery in sparse homogeneous SBM with edge covariates]

Consider an SBM with same-size communities and edge covariate distributions given in (3.1), where  $\tilde{f}, \tilde{g}$  are independent of *n* and  $\rho_n = \log n/n$ . Then, exact recovery is

- solvable if  $\left(\sqrt{a} \sqrt{b}\right)^2 + 2\sqrt{ab}\operatorname{Hel}^2(\tilde{f}, \tilde{g}) > k;$
- unsolvable if  $\left(\sqrt{a} \sqrt{b}\right)^2 + 2\sqrt{ab} \operatorname{Hel}^2(\tilde{f}, \tilde{g}) < k$ .

 $\operatorname{Hel}^{2}(\tilde{f},\tilde{g})$  characterises the additional information gained by observing the edge covariates.

1	Intro	duction
2	Minir	nax rates in mixture models
	2.1	From isotropic to anisotropic GMM
	2.2	(Non-gaussian) mixture models
	2.3	Laplace mixture model
3	Minir	nax rates in Stochastic Block Models
	3.1	Stochastic Block Models
	3.2	Minimax rates in homogeneous SBM
4	Conc	clusion

## CONCLUSION

#### Summary:

- 1. Similarity in the analysis of minimax rates of mixture model and stochastic block models
- 2. Chernoff information is the key quantity

#### **Possible extensions:**

- Mixture models in high dimension (d >> n): isotropic Gaussian done? Ndaoud, 2022; Even et al., 2024
- Mixture models with heavier tails than sub-exponential
- Robustness to perturbations: mixture + random noise, mixture + adversary, mixture + outliers
- (Semi)-supervised rates (Lelarge & Miolane, 2019; Tifrea et al., 2024)

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